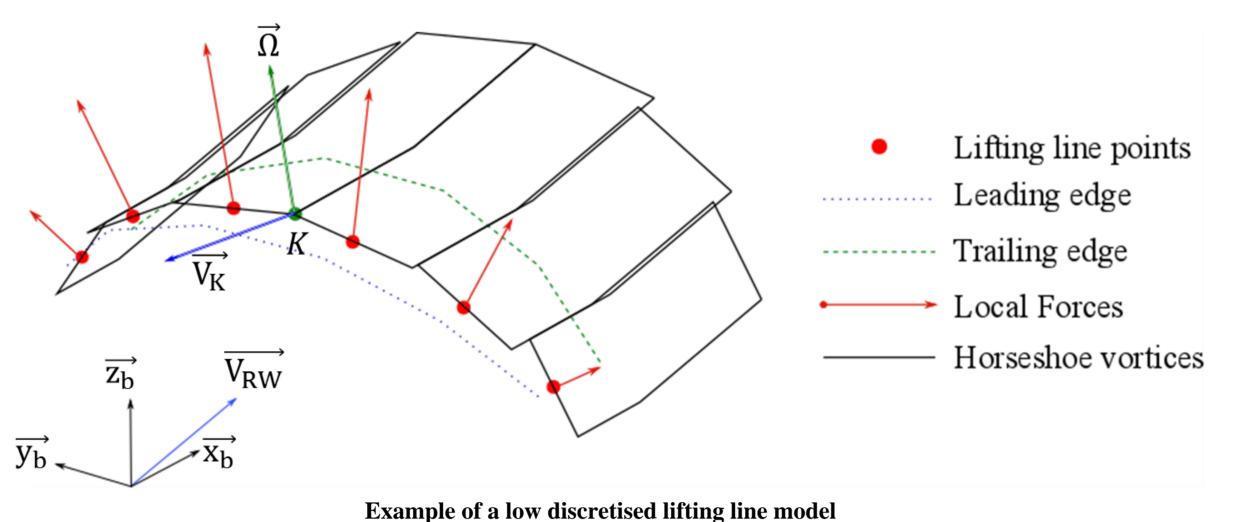
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Kite as a Beam Modelling Approach: Assessment by Finite Element Analysis

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3D non-linear lifting line model [1]



- Prandtl lifting line theory adapted to wings with variable dihedral and sweep angles. Finite wing and its wake represented by a set of horseshoe vortices of different strengths Γ
- Inclusion of the non-linearity of the lift coefficient
- Iterative solution:

Non-linear swept law

--StarCCM+®

─StarCCM+®

—Lifting line

Angle of sideslip (°)

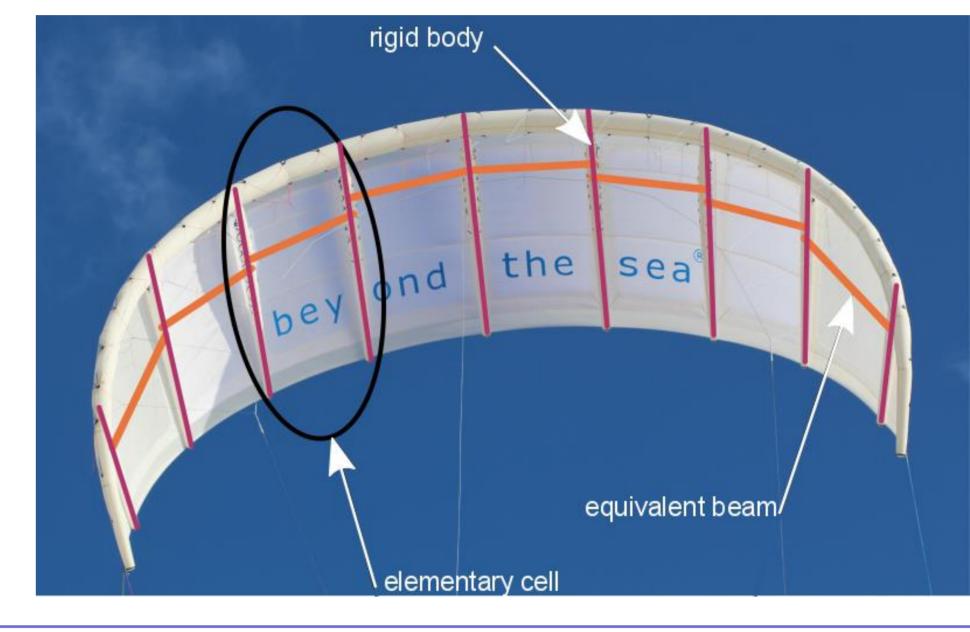
Angle of sideslip: 0°

Angle of incidence: 5°

- Computation of the induced velocities with the Biot-Savart law
- Computation of the circulation from the equivalence between local lift calculated from the Kutta formula and from the polar of the section

Kite as a Beam model [2]

- Kite considered as an assembly of elementary cells
- Cell composed of:
 - Portion of the inflatable leading edge: modelled as a beam
 - Two half inflatable battens: modelled as beams
 - Corresponding canopy: modelled as a shell
- Each elementary cell is replaced by an equivalent beam



Comparison of the 3D non-linear lifting line method with 3D RANSE results (Star-CCM+®) [3]

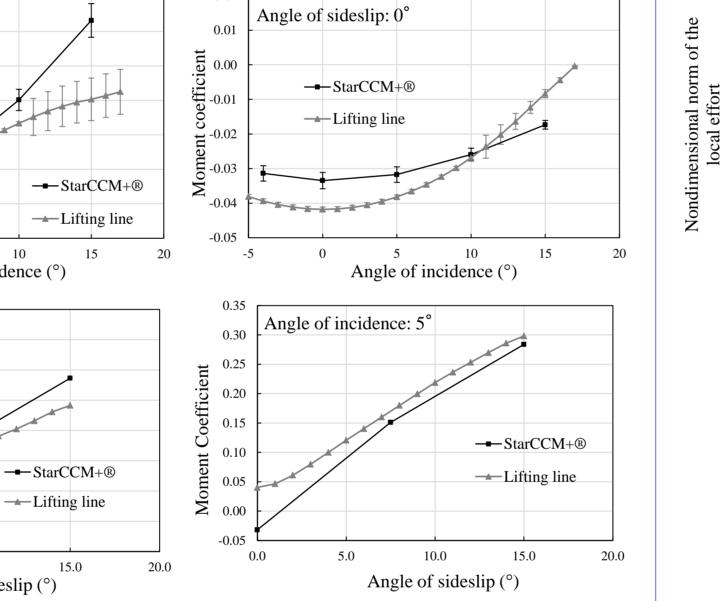
Semi-circular kite of radius 1.0m with a NACA2412 section

0.03

Angle of sideslip: 0°

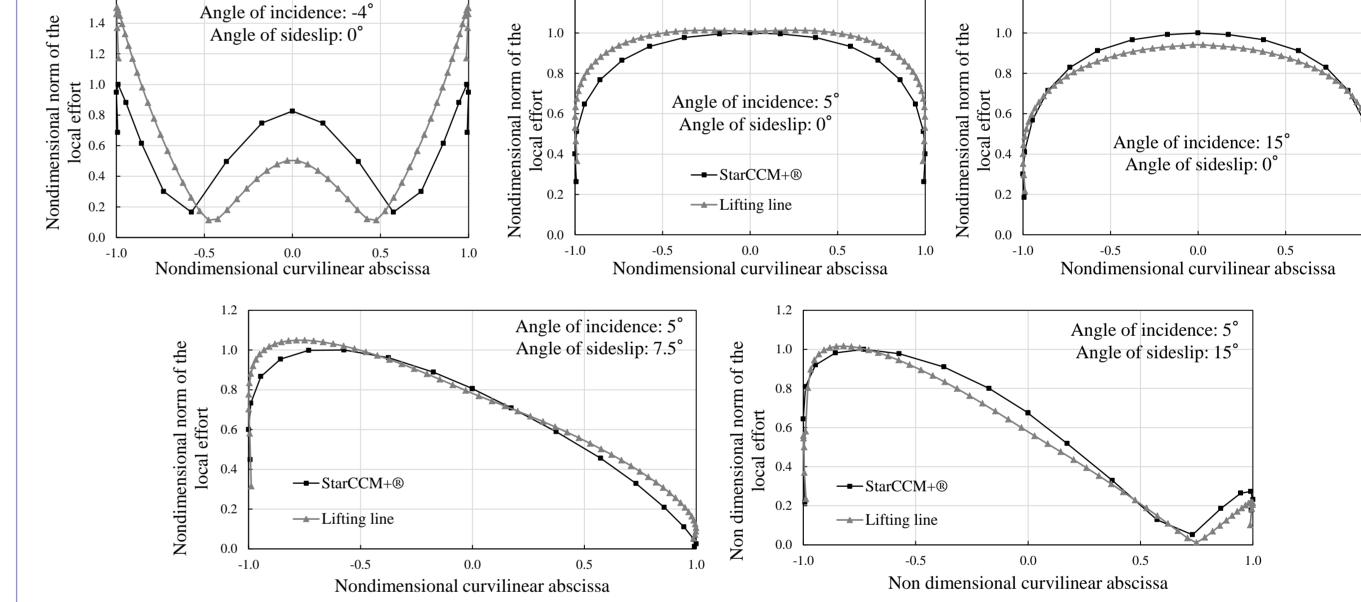
Angle of incidence: 5°

- Linear twist law, from 0° at root to 5° at tips
- Computation time:
 - Lifting line: 0.5s with a standard PC StarCCM+®: 40min with 8 cores
- Non-linear chord law from 1.0m at root to 0.1m at tips



Kite 3D aerodynamic coefficients with respect to the angle of incidence (top) or the angle of sideslip (bottom)

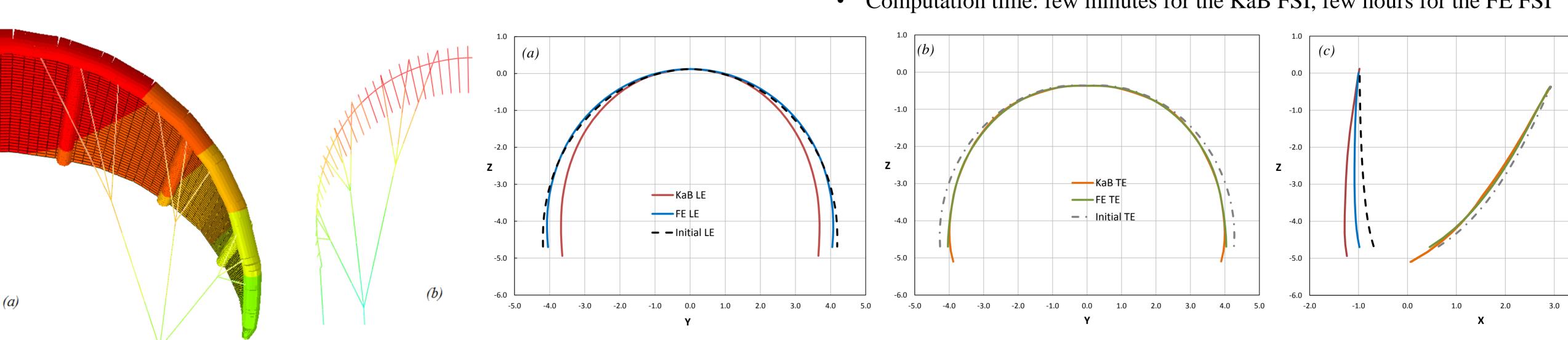
Angle of sideslip (°)



Nondimensional magnitude of the local aerodynamic force per unit length on a kite wing obtained via StarCCM+® (black square) and the lifting line method (grey triangle)

Comparison of the Kite as a Beam model with a Finite Element model [4]

- Fluid-Structure Interaction (FSI) on a $50m^2$ kite at 10° of incidence with an apparent wind of 25m/s and 75m of tether length. The anchor point of the tethers is a fixed point and the tethers and bridles system are represented by truss elements.
 - Comparison between the Kite as a Beam model coupled with the 3D non-linear lifting line method and the Finite Element model coupled with a linear lifting line. The results of the two lifting line are sligthly different.
 - Computation time: few minutes for the KaB FSI, few hours for the FE FSI



(a) Complex Finite Element model with shell and beam elements, (b) Kite as a beam model. The color scale represents the displacement magnitude

(a) Front view of the leading edge (LE) of the kite, undeformed (initial), after convergence with the Kite as a Beam model (KaB), after convergence with the Finite Element model (FE). (b) Front view of the trailing edge (TE) of the kite, undeformed and after convergence with the Kite as a Beam model and the Finite Element model. (c) Side view of the leading and trailing edge of the kite, undeformed and after convergence of the two models.

Acknowledgements:

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References:

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[3] Duport C., Deberque M., Leroux J.-B., Roncin K., Jochum C.: Local results verification of a 3D non-linear lifting line method for Fluid-Structure interaction simulation on a towing kite for vessels. In: Proceedings of the 11th Symposium on High-Performance Marine Vehicles, Zevenwacht, South Africa, 11-13 Sep 2017.

[4] Maison A., Nême A., Leroux J.-B.: De la problématique du dimensionnement de grands kites. In: ATMA 2017















----KaB LE

—— KaB TE

——FÉ LE

——FÉ TE

– Initial LE

Initial TE